



# Transformer Magnetic Circuit

Transformer Concepts & Applications Seminar  
Goldsboro, NC  
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# Jason Nelson

## Principal Design & Development Engineer

Jason joined Prolec GE Waukesha in July 2005 as a design engineer at our Goldsboro, North Carolina, facility. He designs medium power transformers, including LTC and re-connectable types. He also works on updating and maintaining design software for the plant. Jason earned his Bachelor of Science, Electrical Engineering and Computer Engineering Degrees from North Carolina State University.



# Agenda

- Transformer Fundamentals
- Core Loss
- Core Steel
- Core Types
- Core Design & Construction
- Core Related Problems & Solutions

# Transformer Fundamentals

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$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \left( \mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

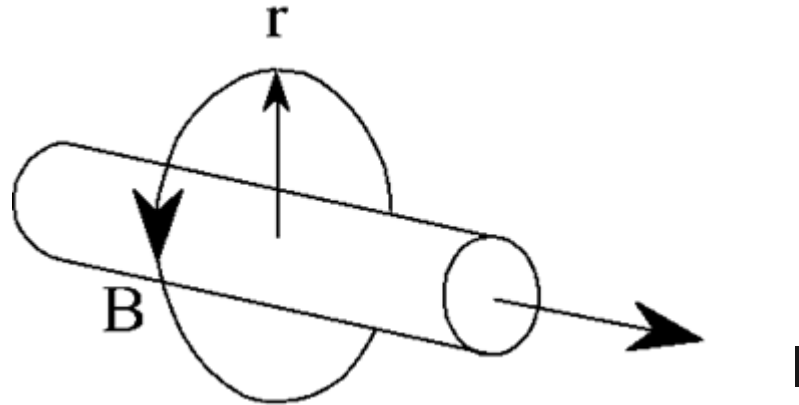
$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

# Magnetic Terms

- Magnetomotive Force – MMF
  - Symbol ( $\mathcal{F}$ )
  - ~ EMF that causes current flow
  - Unit: ampere-turn
- Flux
  - Symbol ( $\phi$ )
  - # of magnetic field “lines”
  - Unit: weber
- Magnetic Flux Density
  - Symbol ( $\mathbf{B}$ )
  - Flux concentration
  - Unit: tesla
- Magnetic Field Intensity
  - Symbol ( $\mathbf{H}$ )
  - MMF distribution along magnetic path
  - Unit: amp-turns/meter

# Currents & Magnetic Fields



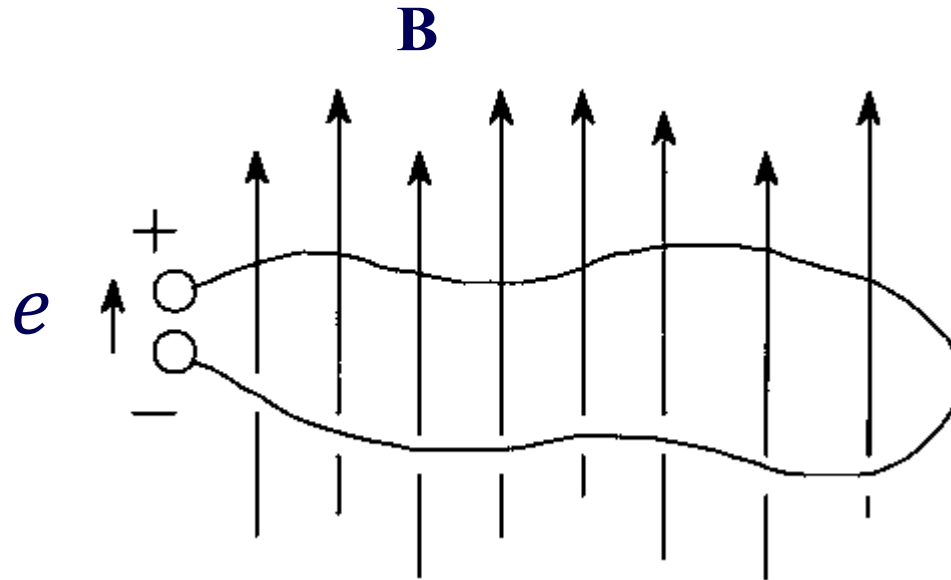
**B** field surrounding conductor carrying current  $I$

## Right-Hand Rule

- Thumb in direction of current
- Fingers in direction of magnetic field

Magnetic field intensity (**H**) inversely proportional to distance ( $r$ )

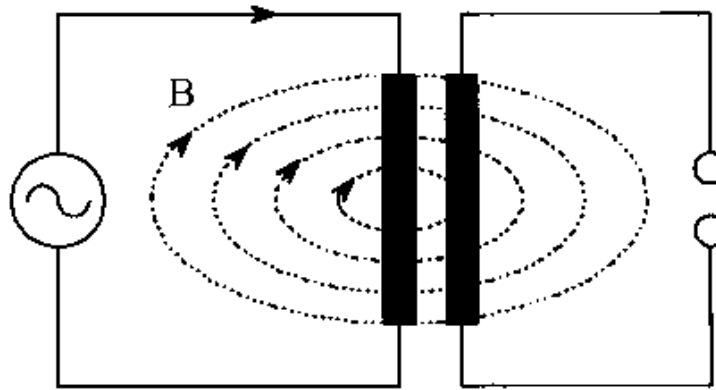
# Magnetic Induction



*Voltage induced in a loop  
surrounding a time-varying  $B$  field*

Time-varying flux = induced voltage  $e$   
around closed path surrounding  $\phi$

# Faraday's Law of Induction



$e$  Voltage induced in a conductor

$$\text{EMF is: } = -N \frac{d\Phi_B}{dt}$$

## Law of induction

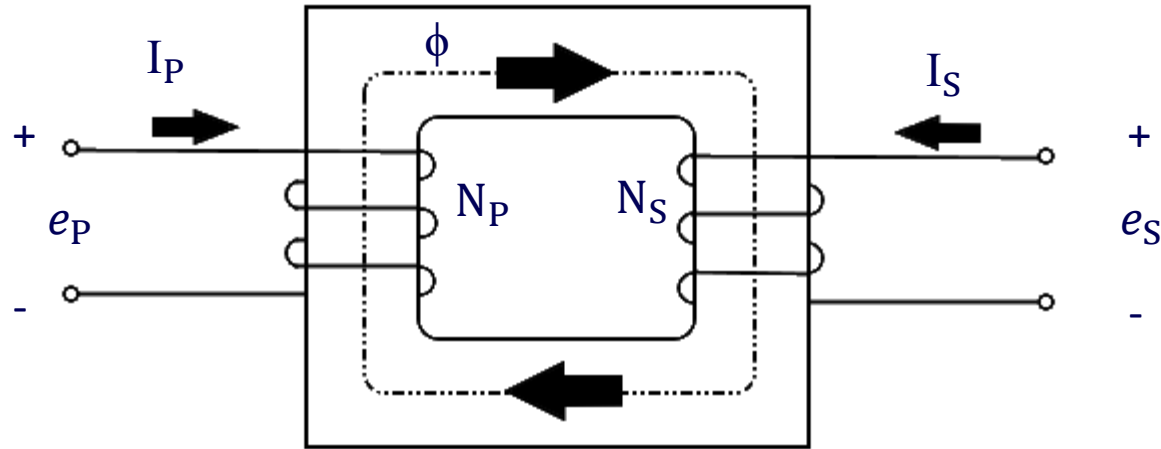
- Induced voltage  $e$  around path surrounding time-varying flux

## Not efficient in air

- Low % age of flux linked to secondary circuit



# Ideal Transformer



$$\frac{e_P}{e_S} = \frac{I_S}{I_P} = \frac{N_P}{N_S}$$

$$e_P = \sqrt{2}\pi f \phi_m N_P$$

$$\frac{\text{Volts}}{\text{Turn}} = \sqrt{2}\pi f \phi_m = 4.44 f B_m A$$

Where,

$e$  = voltage (volts – primary or secondary)

$I$  = current (amps – primary or secondary)

$A$  = core cross section area (sq. m)

$B$  = flux density (Tesla)

$\phi$  = flux (webers)

$f$  = frequency (Hz)

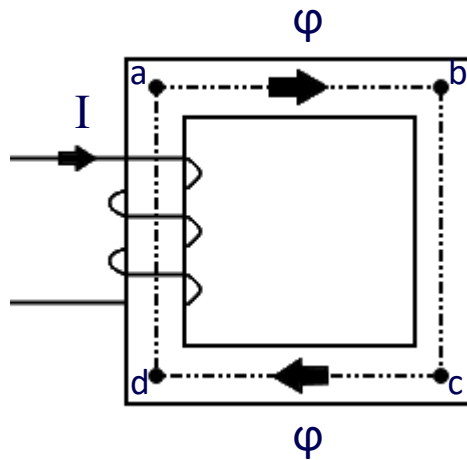
# Permeability

- Introduction of core (coupling medium)
  - Magnetic material with affinity for flux
  - Increase in total flux linkage
  - Channeling (linking) coils with high %age of flux
  - Efficiency greatly increased
  - Lower magnetizing current
  - Higher ratio of mutual to leakage flux = reduced stray losses
- Degree of magnetization of material in response to magnetic field

$$\mu = \frac{\mathbf{B}}{\mathbf{H}} = \frac{\text{flux density}}{\text{field intensity}}$$

- Grain-oriented silicon steel conducts flux 1500x vacuum
- For core materials  $\mu$  varies with flux density and ranges from ~ 200 - 100,000
- For non-magnetic materials  $\mu \approx 1 - 10$

# Magnetic Circuit



	<u>Magnetic</u>		<u>Electric</u>
Magnetomotive Force	$\mathcal{F}$		Electromotive Force $e$
Magnetic Intensity	$\mathbf{H}$		Electric Intensity $\mathbf{E}$
Flux Density	$\mathbf{B}$		Current Density $\mathbf{J}$
Flux	$\phi$		Current $I$
Reluctance	$\mathcal{R}$		Resistance $R$
Permeability	$\mu$		Conductivity $\sigma$

## Analogous Magnetic and Electric Quantities

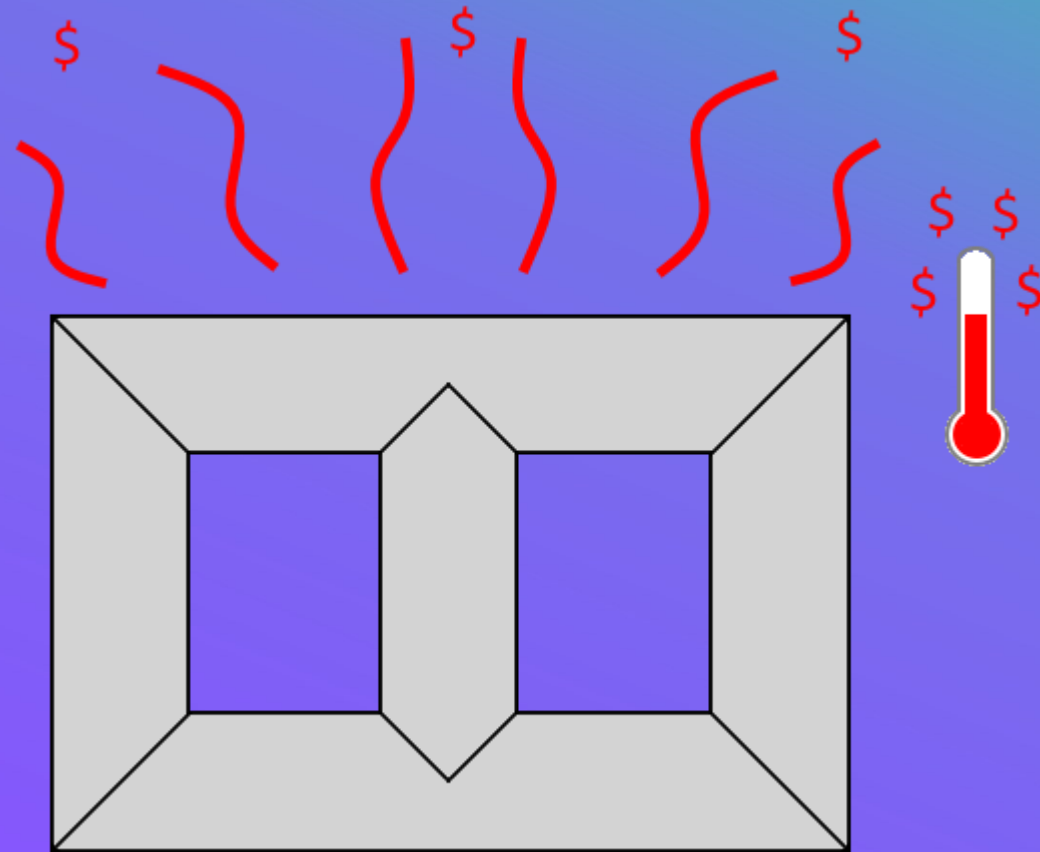
- $\mathcal{R}$  = reluctance of magnetic circuit a-b-c-d-a
- Reluctance: property that resists magnetic flux
- Coil wound around magnetic yoke
- Coil with  $N$  turns carrying current  $I$
- Flow of magnetic flux along path a-b-c-d-a

	<u>Magnetic</u>	<u>Electric</u>
Ohm's Law	$\mathcal{F} = \phi \mathcal{R}$	$e = IR$
KVL (around loop)	$\sum_i \mathcal{F}_i = \sum_i \phi_i \mathcal{R}_i$	$\sum_i e_i = \sum_i I_i R_i$
KCL (at a junction)	$\sum_i \phi_i = 0$	$\sum_i I_i = 0$

## Analogous Magnetic and Electric Equations

# Core Loss

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# Core Loss

Core Loss means heating of core material

## Eddy Loss

- Results from eddy currents circulating
  - Induced by flux flow normal to core width
- Can be reduced by
  - Reduced thickness
  - Application of thin insulating coating

## Hysteresis Loss

- Results from cyclical reversal of flux
  - “Friction” during realignment of magnetic domains every half-cycle
- Can be reduced by metallurgical control of steel

# Eddy Loss

Proportional to

- Core steel conductivity
- Steel thickness, flux density, and frequency squared

Where,

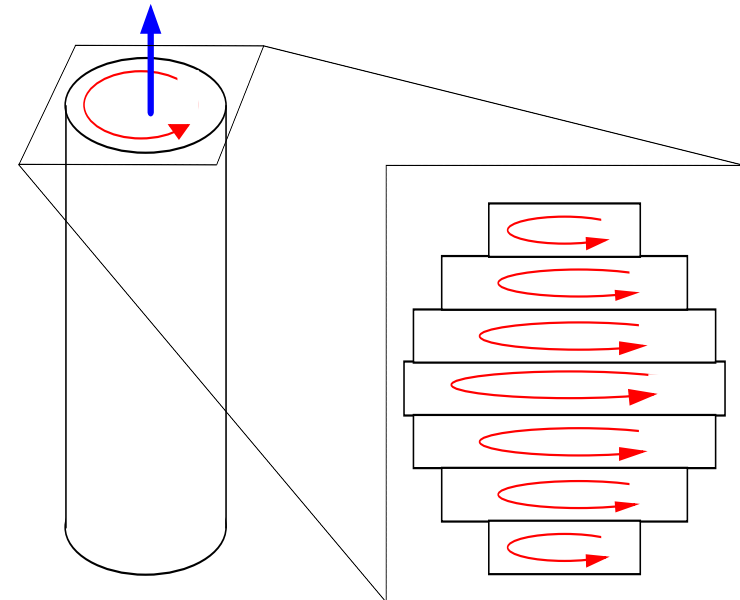
$K_e$  = material constant

$f$  = frequency (Hz)

$B$  = max flux density (Tesla)

$\tau$  = lamination thickness (mm)

$v$  = material volume (cu meters)

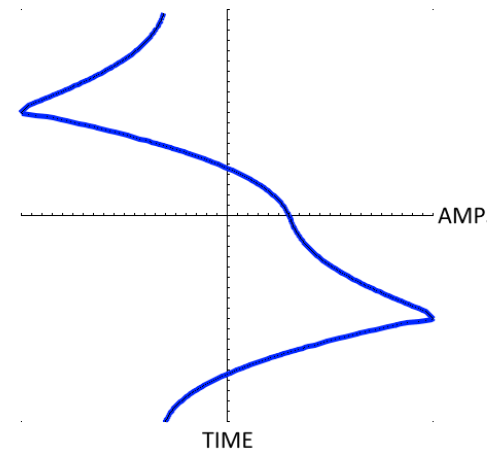
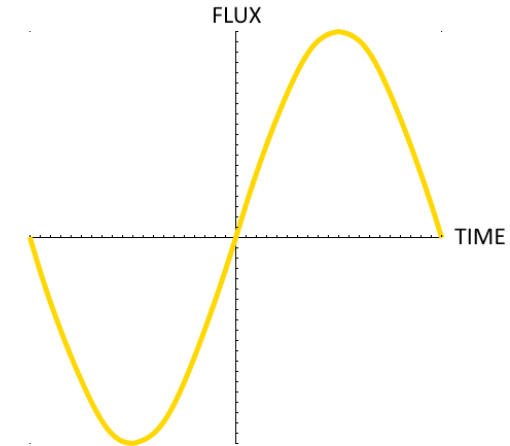
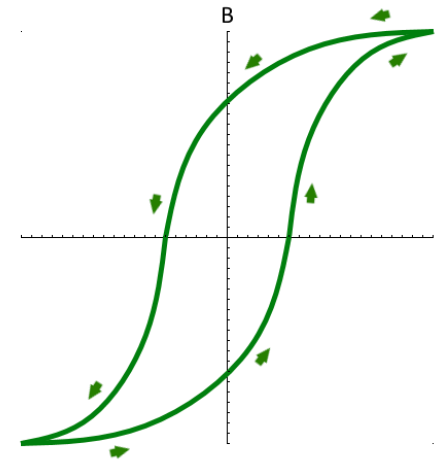


$$P_e = K_e f^2 B_m \tau^2 v$$

# The B-H Curve

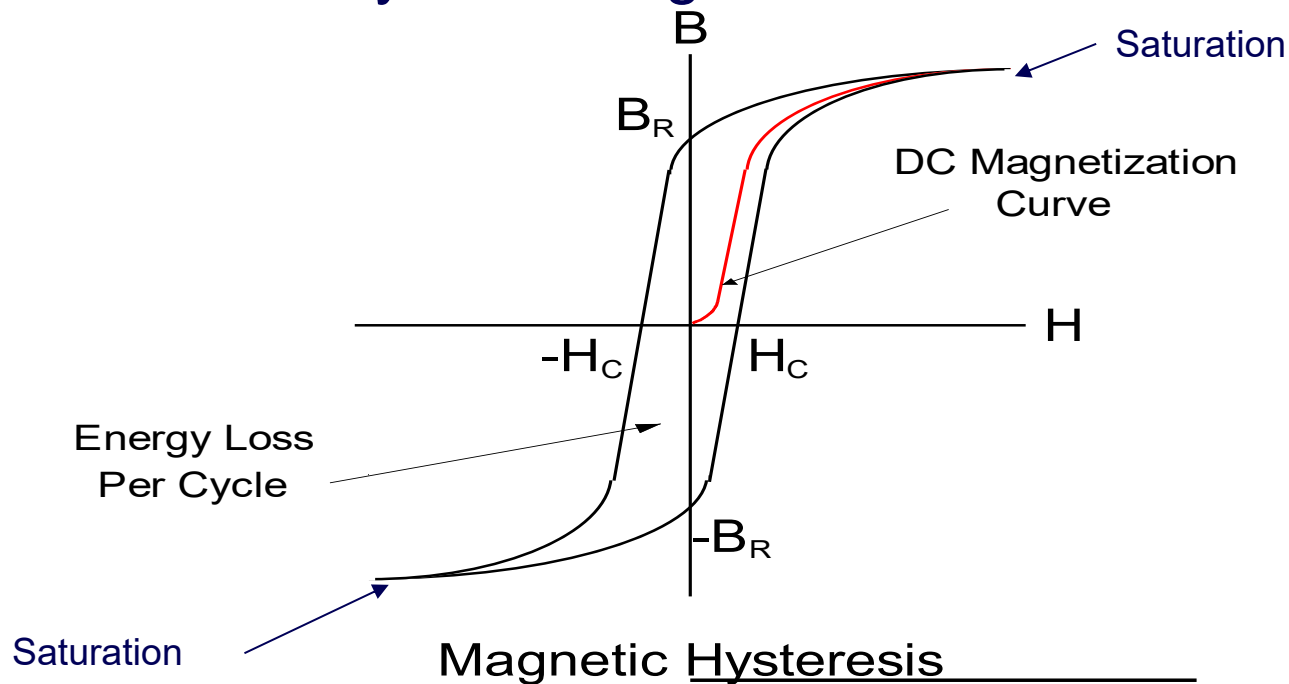
Depends on

- Magnitude of flux density
- Periodic frequency
- When magnetizing current = 0, considerable +ve or -ve residual flux
- Residual flux is from magnetically aligned crystalline structures
- Saturation
  - $H \uparrow$ ,  $B \uparrow$  at **smaller** rate
  - $\mu \downarrow$  as  $B \uparrow$
- Occurs at approx. +/- 1.5T
  - Typical for materials used in power transformers



# Hysteresis Loss

- Ferromagnetic core material exhibits "*memory*" which causes hysteresis loss in transformers
- Area bounded by the hysteresis loop represents the energy lost during each cycle of magnetization



$$P_h = vf ( K_h B^n )$$

Where,

$v$  = volume (cu meters)

$f$  = frequency (Hz)

$K_h$  = material constant

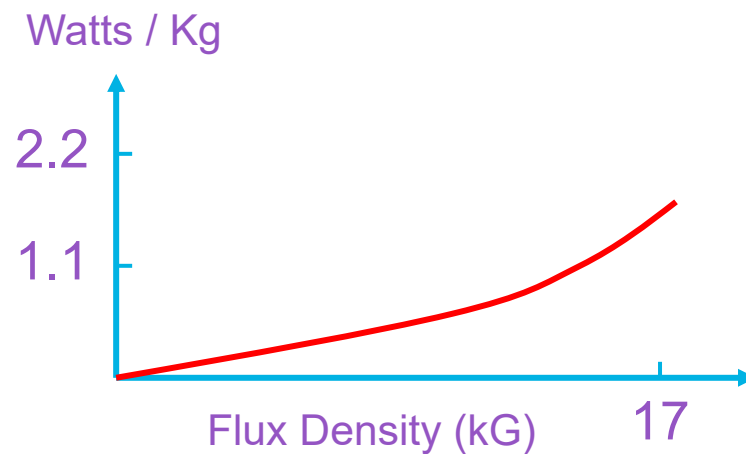
$B_m$  = max flux density (Tesla)

$n$  = material constant (1.5 to 2.5)



# Core Loss Calculation

- The loss density of a ferromagnetic material increases almost exponentially with flux density (**B**).
- Core loss = Core weight x Watts/kg x Destruction Factor

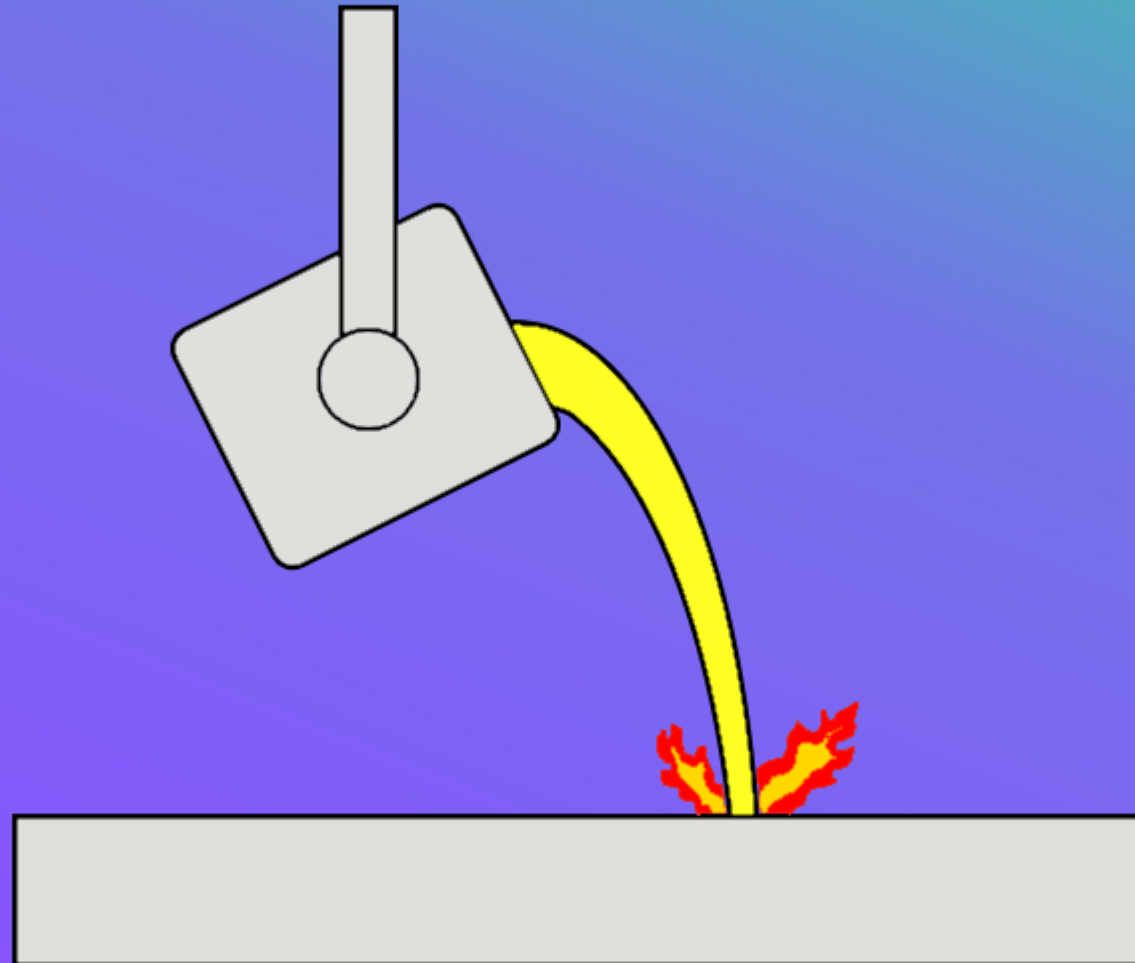


Typical Curve of Core Loss  
vs. B at 60 Hz

- The loss density of different electrical steels is commonly compared under standard operating conditions.

# Core Steel

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# Early Years

## Inferior grades of laminated steels

- Higher core losses
- Pronounced aging effects
- Increased hysteresis losses

## Silicon alloyed with low carbon content steel

- Low hysteresis losses
- Improved permeability
- Reduced magnetizing current

# Increased Efficiency

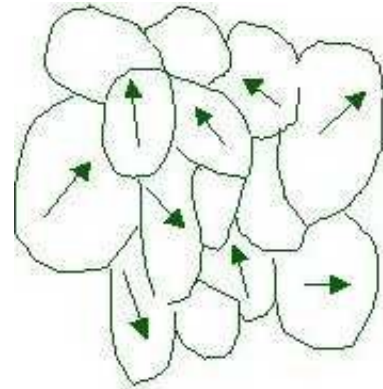
## CRGOS (Cold Rolled Grain-Oriented Silicon Steel)

Silicon-iron alloy rolled such that permeability is higher and hysteresis losses are lower when flux is in direction of grain

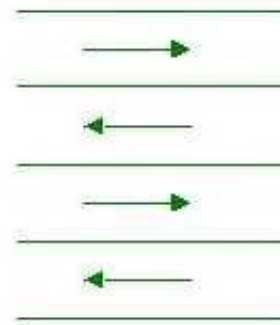
- Pros
  - Magnetic flux flow along grain orientation = min losses
  - Increased power ratings
  - Reduced core losses
- Cons
  - Susceptible to increased losses due to flux flow in other directions, mechanical strain, jointing, bending etc.

# Magnetic Domains

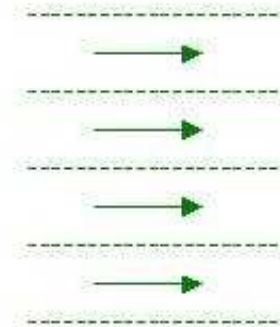
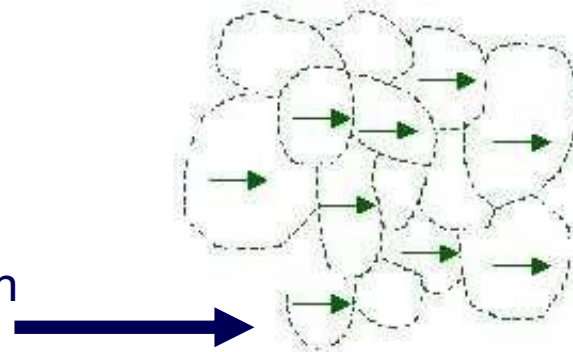
Hot rolled  
(random orientation)



Cold rolled  
(grain-orientated)



Without magnetic field



With magnetic field



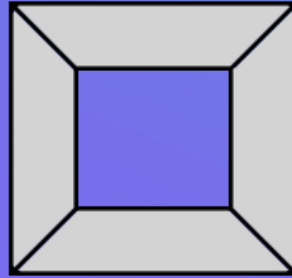
# Electrical Steels

## Common Grades of Electrical Steels

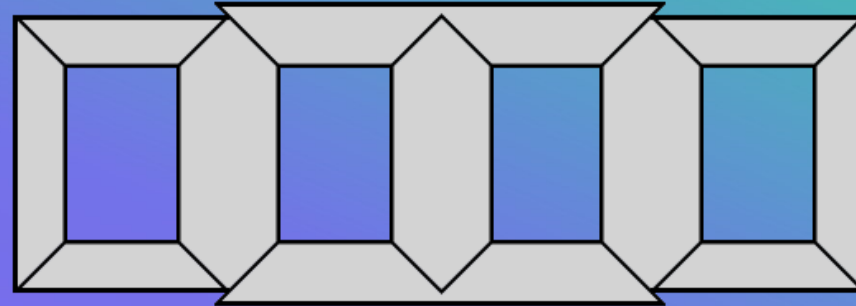
Process	Type	Grade		
Hot Rolled	Non Oriented (1900)*	M-47		M-27
		M-45		M-22
		M-43		M-19
		M-36		M-15
Cold Rolled	Grain Oriented (1934)*	M-6		M-3
		M-4		M-2
	Super Grain Oriented (1968)*	H-2	H-1	H-0
		Domain Refined Super Grain Oriented (1984)*		

\* approximate date of first commercial product

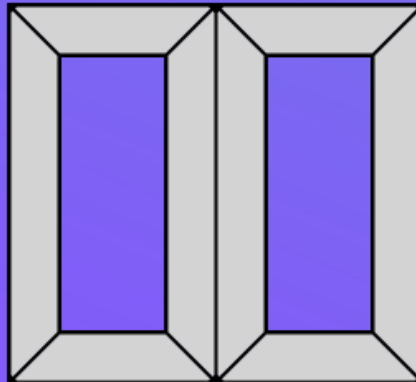
# Core Types



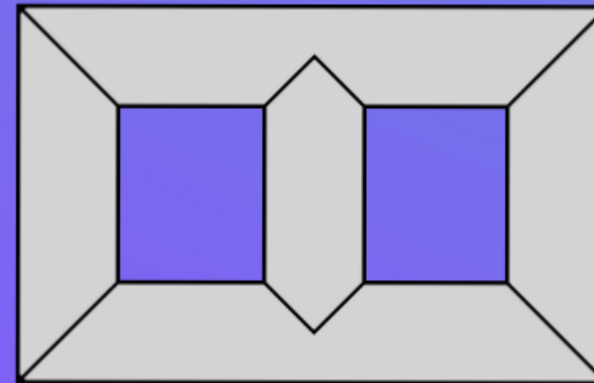
Single phase 2-limbed core



3 phase 5-limbed core



Single phase  
3-limbed core



3 phase 3-limbed core

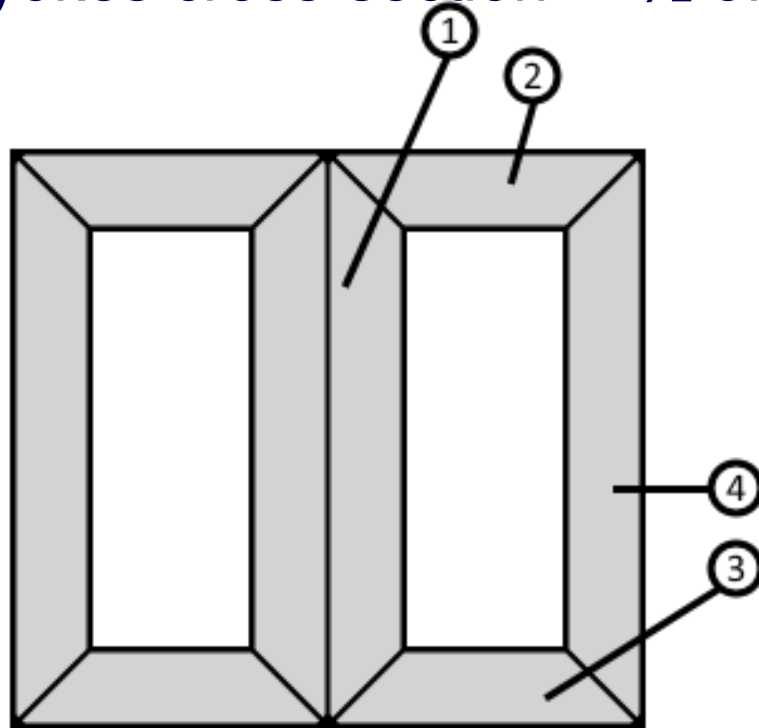
# Core Types

- Single phase 2-limbed core
- Single phase 3-limbed core
- 3 phase 3-limbed core
- 3 phase 5-limbed core



# Single-Phase 3-Limbed Core

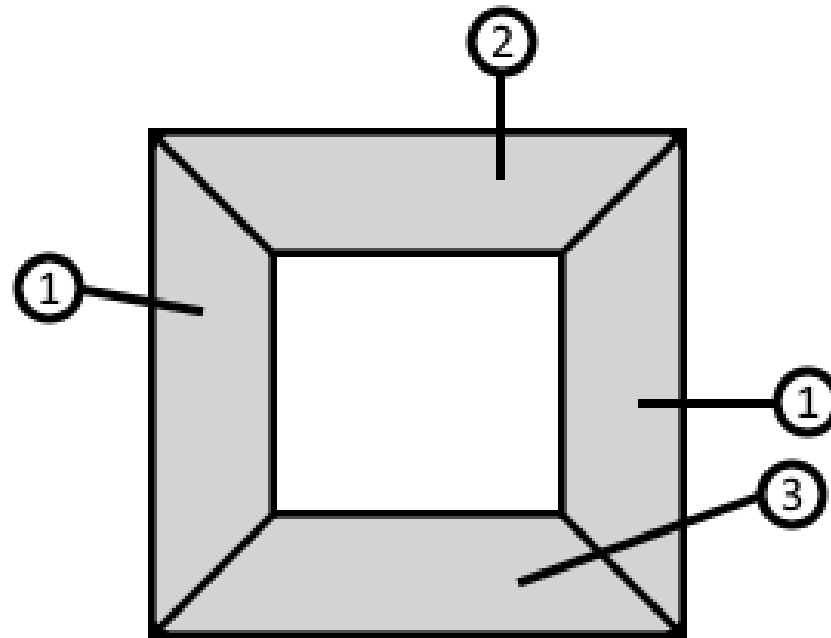
- Main magnetic flux divided into 2 parallel return paths
- Aux limbs, yokes cross-section =  $\frac{1}{2}$  of main limb



Single-phase three-limbed core:  
(1) main limb, (2) top yoke,  
(3) bottom yoke, (4) aux limb.

# Single-Phase 2-Limbed Core

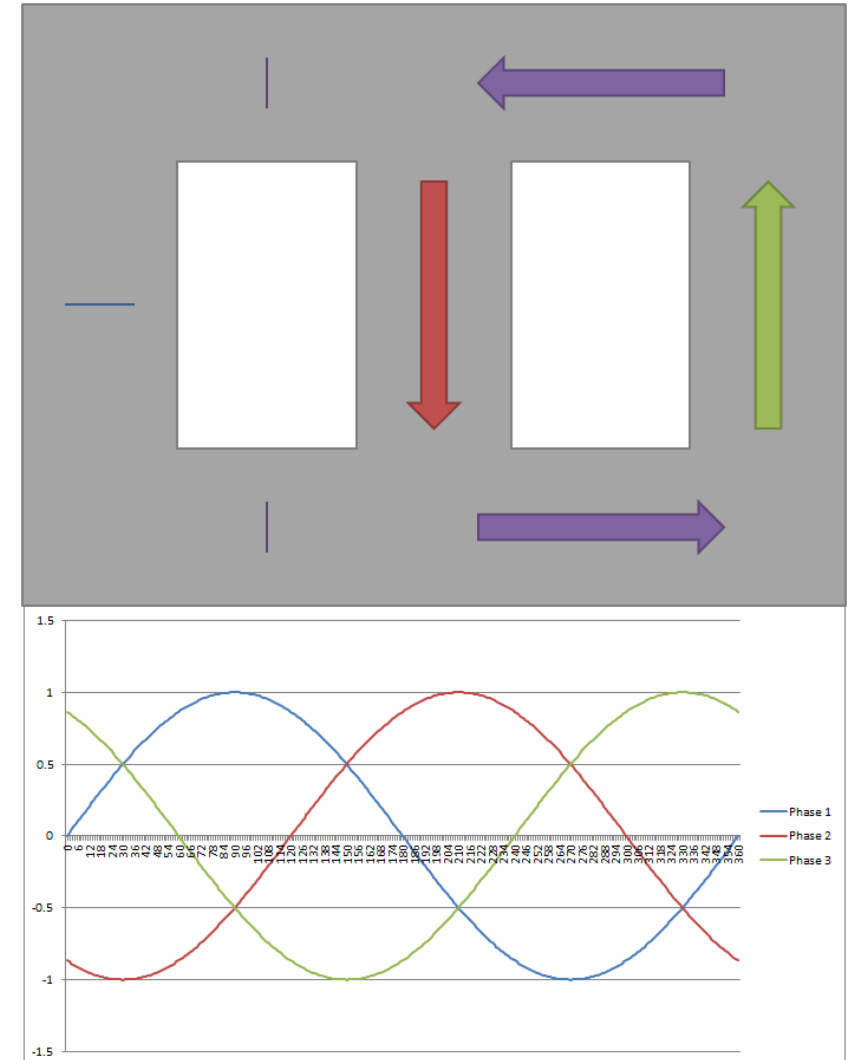
- Cross-sectional area of legs & yokes same
- Windings split into 2 → higher % age leakage reactance



Single-phase two-limbed core:  
 (1) main limb, (2) top yoke,  
 (3) bottom yoke

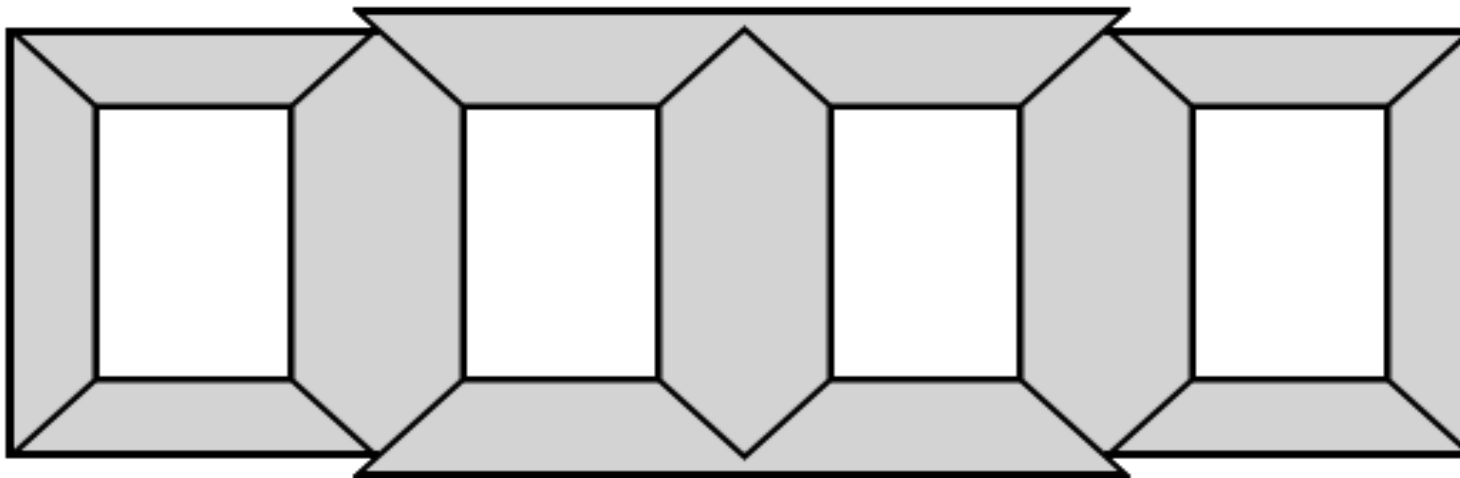
# 3-Phase 3-Limbed Core

- 1 leg per phase
- Yokes & 2 limbs provide return path to flux of 1 limb
- At any instant of time, phase fluxes
  - $\Phi_A + \Phi_B + \Phi_C = 0$
- Legs & yokes have identical cross-section
- More economical vs. bank of three 1-phase transformers
- Restricts 3<sup>rd</sup> harmonic flux and allows for a distortion-free secondary voltage wave shape



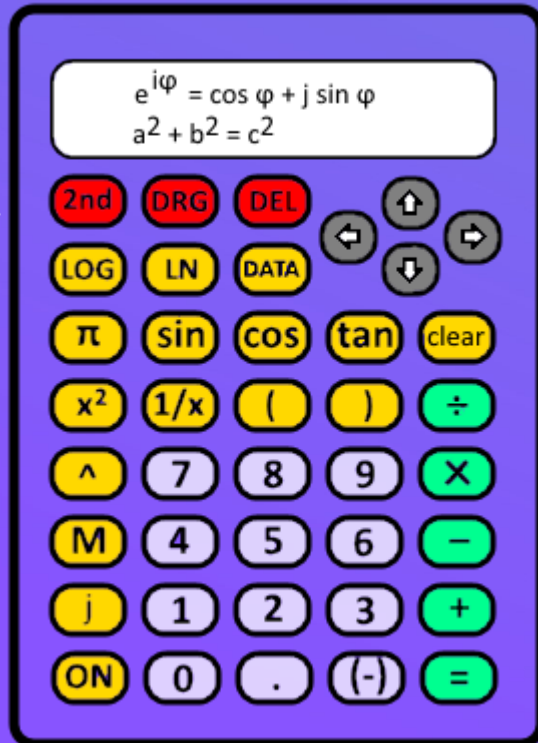
## 3-Phase 5-Limbed Core

- Large power rated XFMRs → large diam cores →
- Increased core height → transportation problems
- Yoke cross section reduced ~40%
- Aux yokes & limbs provide return path to flux
- Cross section & height of aux yokes & limbs < main yokes





# Core Design & Construction

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# Design of Magnetic Circuit

- MVA rating of transformer
  - Performance parameters
    - Impedance
    - BIL
    - kV class
  - Operational conditions
  - Sound level requirements
  - No-Load loss evaluation  
\$/kW
  - Transport limitations
- Magnetic flux density saturation of  
CRGOS
    - Core saturation dependent on input voltage  
and frequency
    - Suitable value to avoid saturation
  - Increased magnetic flux density
    -  Core weight
    -  Core losses

# Core Design & Construction

## Air gaps = Reluctance

- Reduce inductance of coil, increase magnetizing currents
- Eliminate all air gaps?

## Approach 1: Core from solid block

- Impractical
  - Coils wound through core window
- Large circulating currents
  - Oppose changing flux
  - Effectively “short out” transformer

# Core Design & Construction (cont.)

## Approach 2: Thin laminated steel sheets stacked together

- Excellent magnetic properties
- Relatively inexpensive
- 0.010” – 0.020” thick
- Formed from steel ribbon
  - Cut into sections by Georg
  - Various sizes and shapes







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# Core Steel Laminations

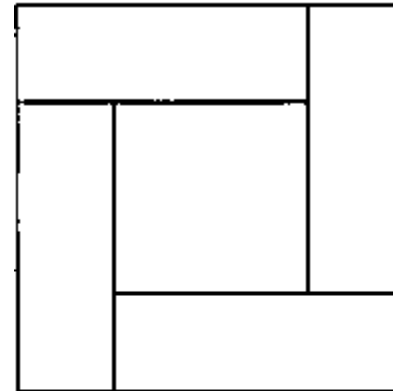
- Carlite – Oxide coating for insulation
- Stacking factor
  -  with thicker laminations =  eddy current (proportional to square of thickness)
  -  with thinner laminations =  eddy current (preferred)
  - Deburring
    - Improves stacking factor
    - Minimizes eddy losses

# Core Stacking Methods

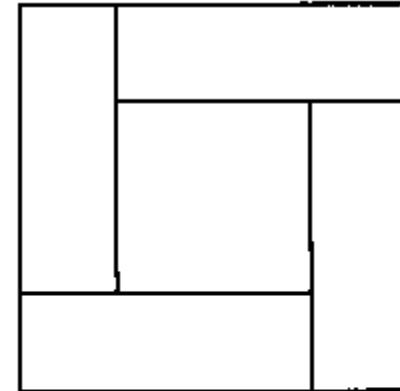
## Butt Lap Method

- Edges butted
  - Alternating layers assure continuous
  - path across surfaces
- Simple in terms of manufacturing
- Higher losses
- Works best with non grain-oriented steel
- Small rating transformers

Even Layer



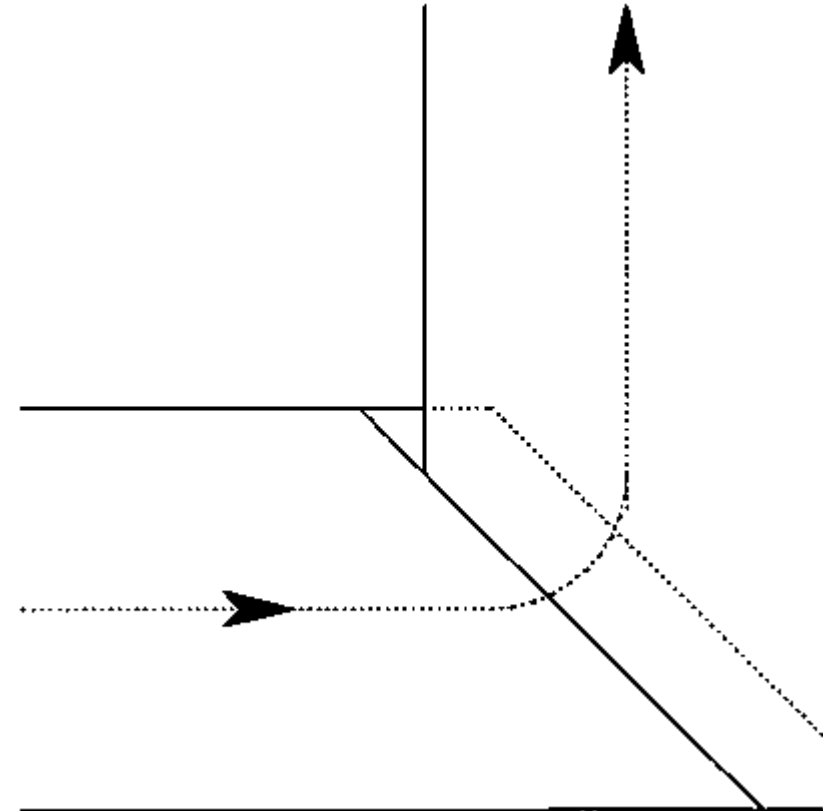
Odd Layer



# Core Stacking Methods (cont.)

## Mitered Joints

- Corners cut at 45°
- Alternate layers
  - Cut into slightly different lengths
  - Have slightly different shapes
- Smooth path of flow for magnetic flux
- Grain oriented along lengths in horizontal and vertical directions
- Losses minimum
- Extra manufacturing cost

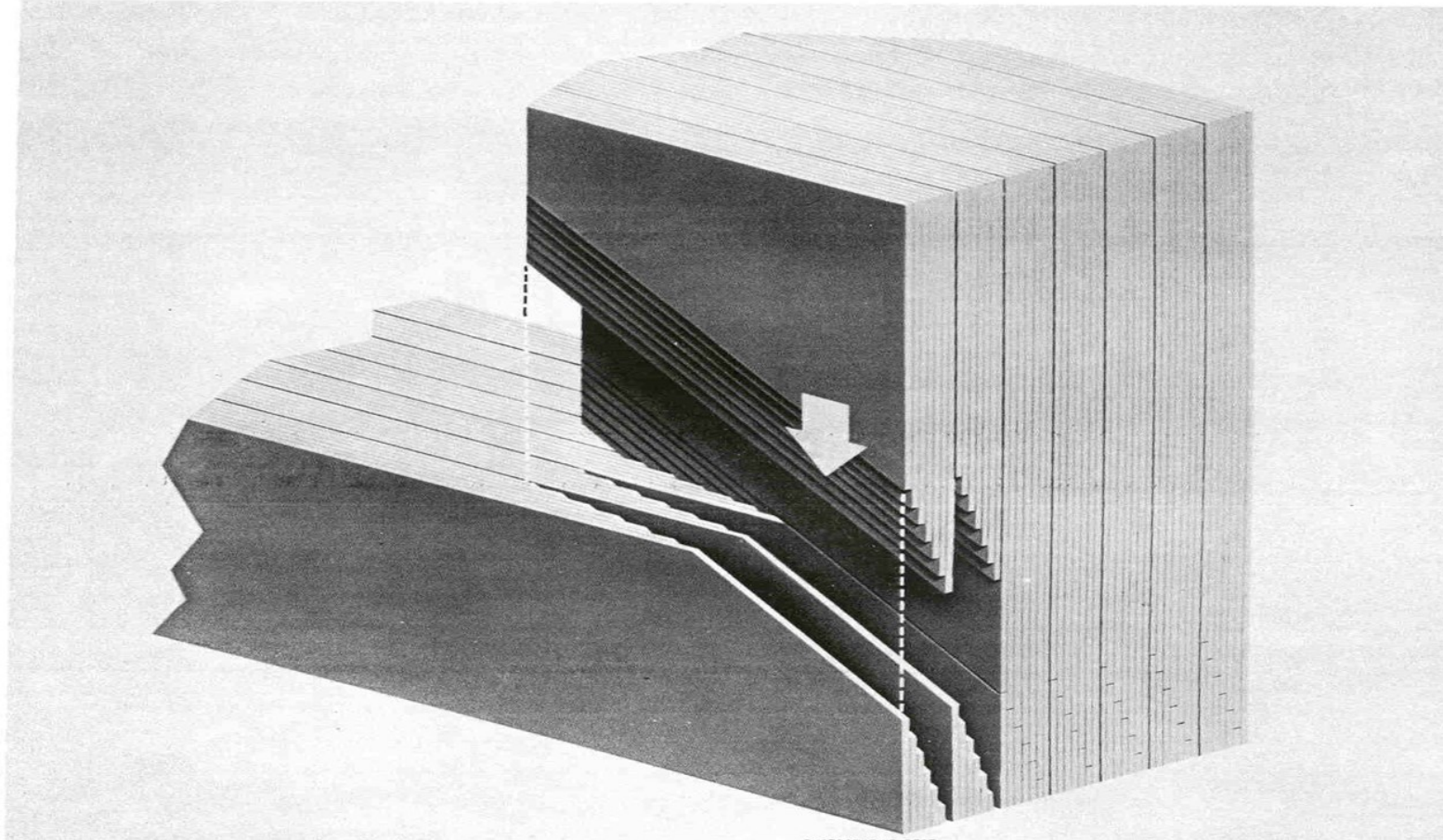


Flux transition at the corner of a mitered core

# 5 Step Lap

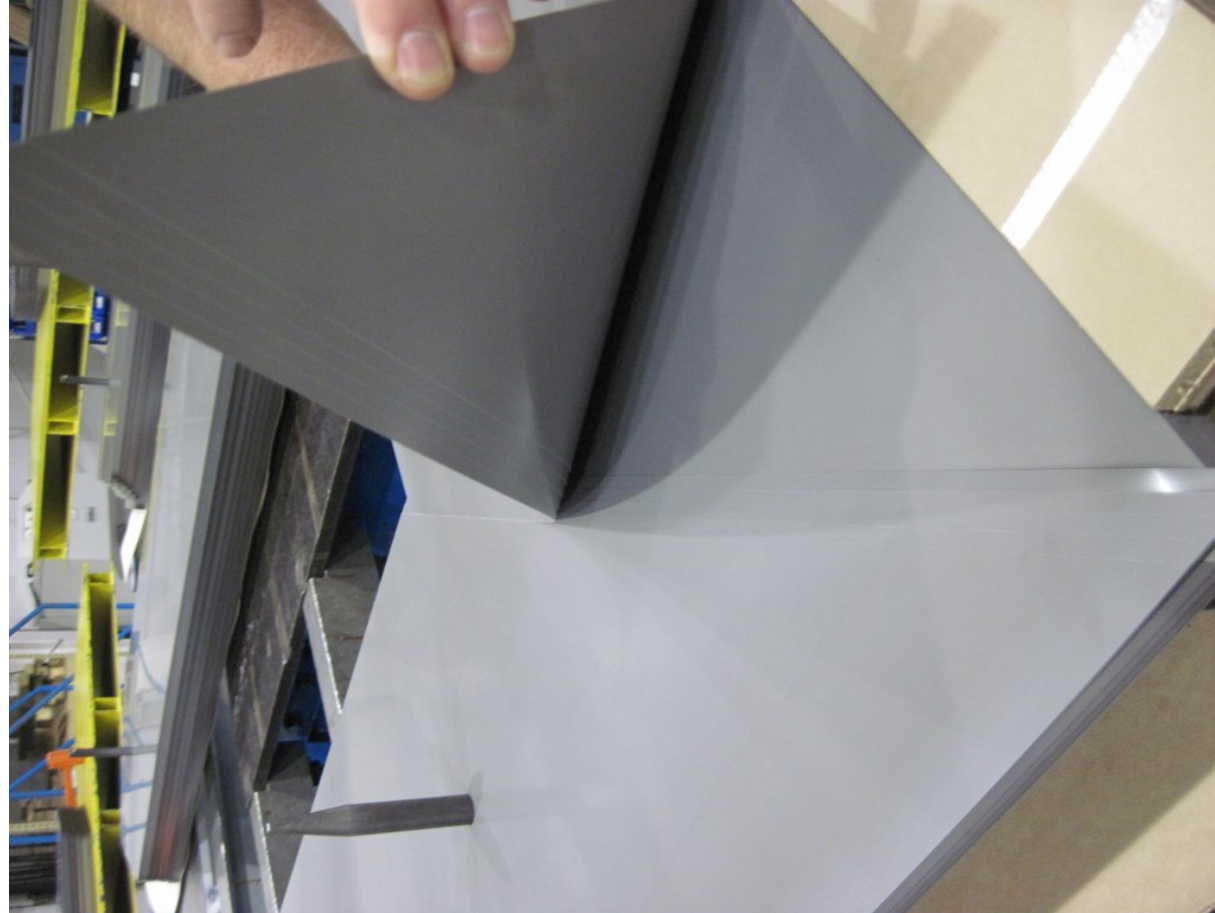


# Step Lap Joint



Corner Joints: Step Lap Detail (7-step lap shown)

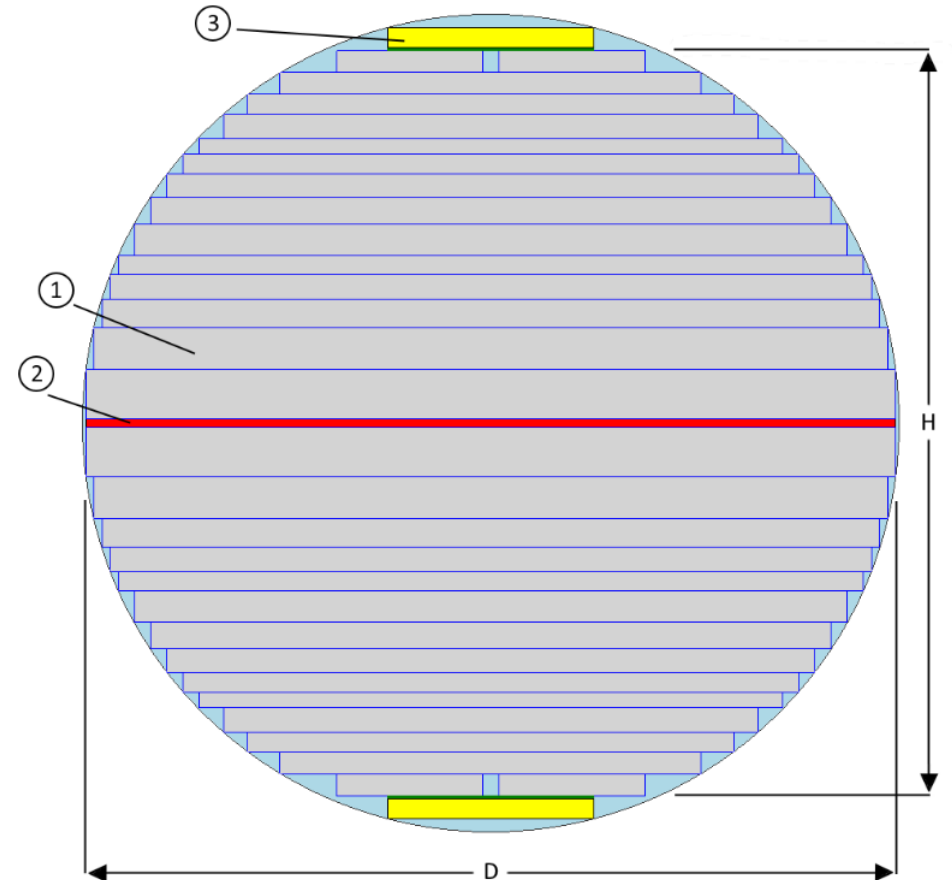
# Step Lap Joint (cont.)



Corner Joints: 5-step lap shown

# Optimum Design of Core

- Ideal shape: Circle
  - No wasted space besides insulation space
  - Possible but uneconomical
- Varying widths & packet heights approximate a circle
- Within core circle
  - Steel sheet laminations
  - Oil duct
  - Clamp plates
- Stacking factor: space lost between laminations
  - Burrs lower stacking factor

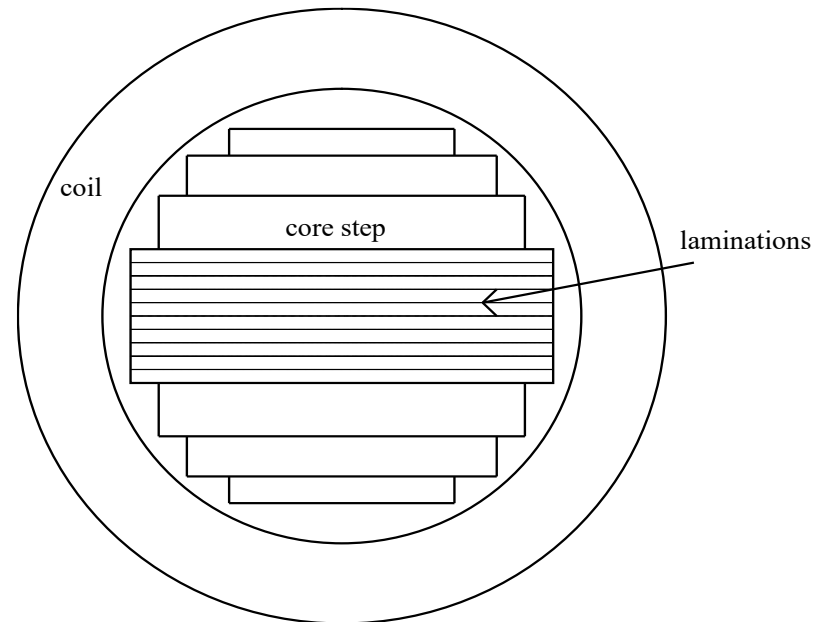


Circular core cross section: D - diameter of core, H - total lamination stack height (1) laminations, (2) oil duct, (3) steel clamp plates.

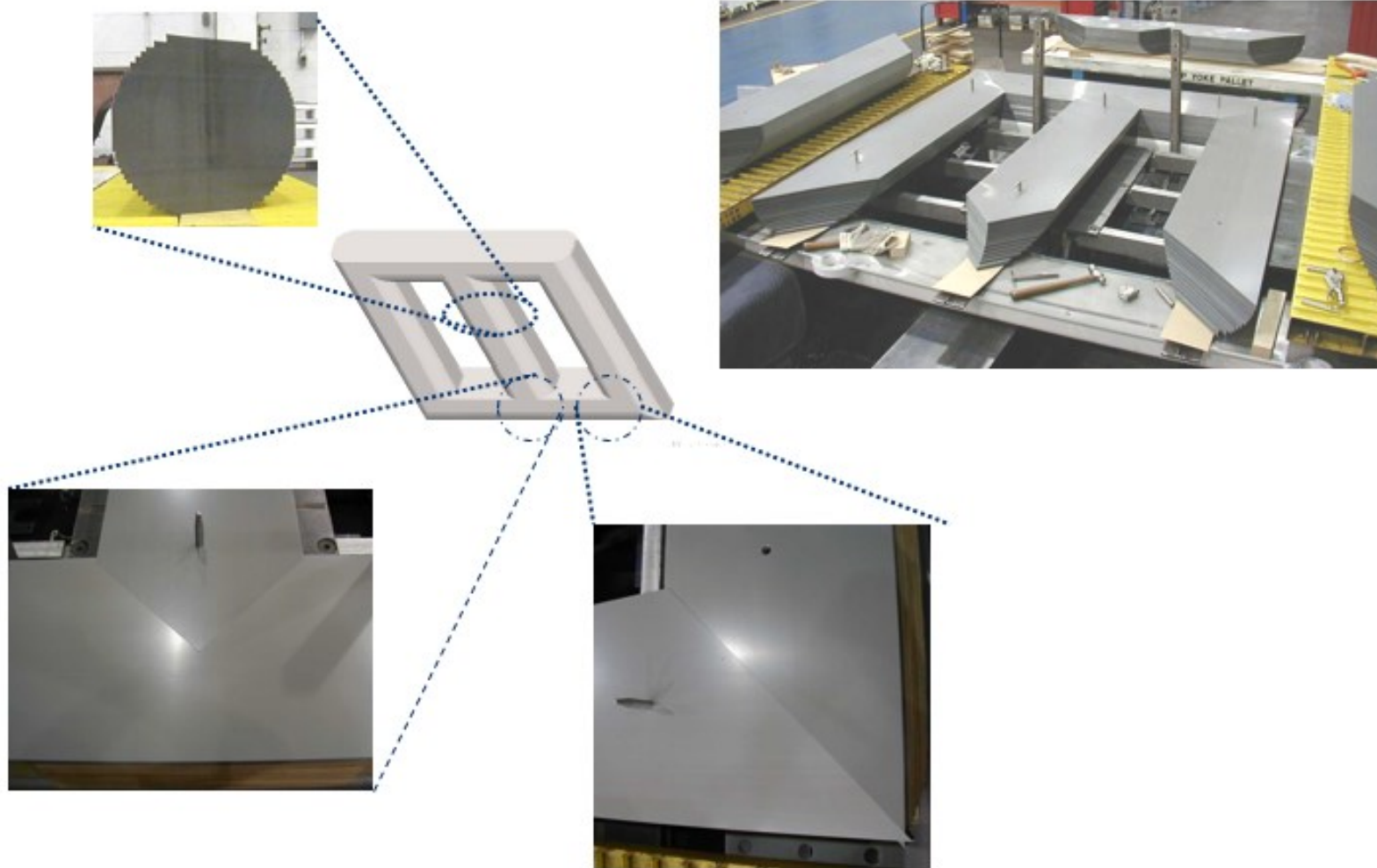


# Optimum Design of Core (cont.)

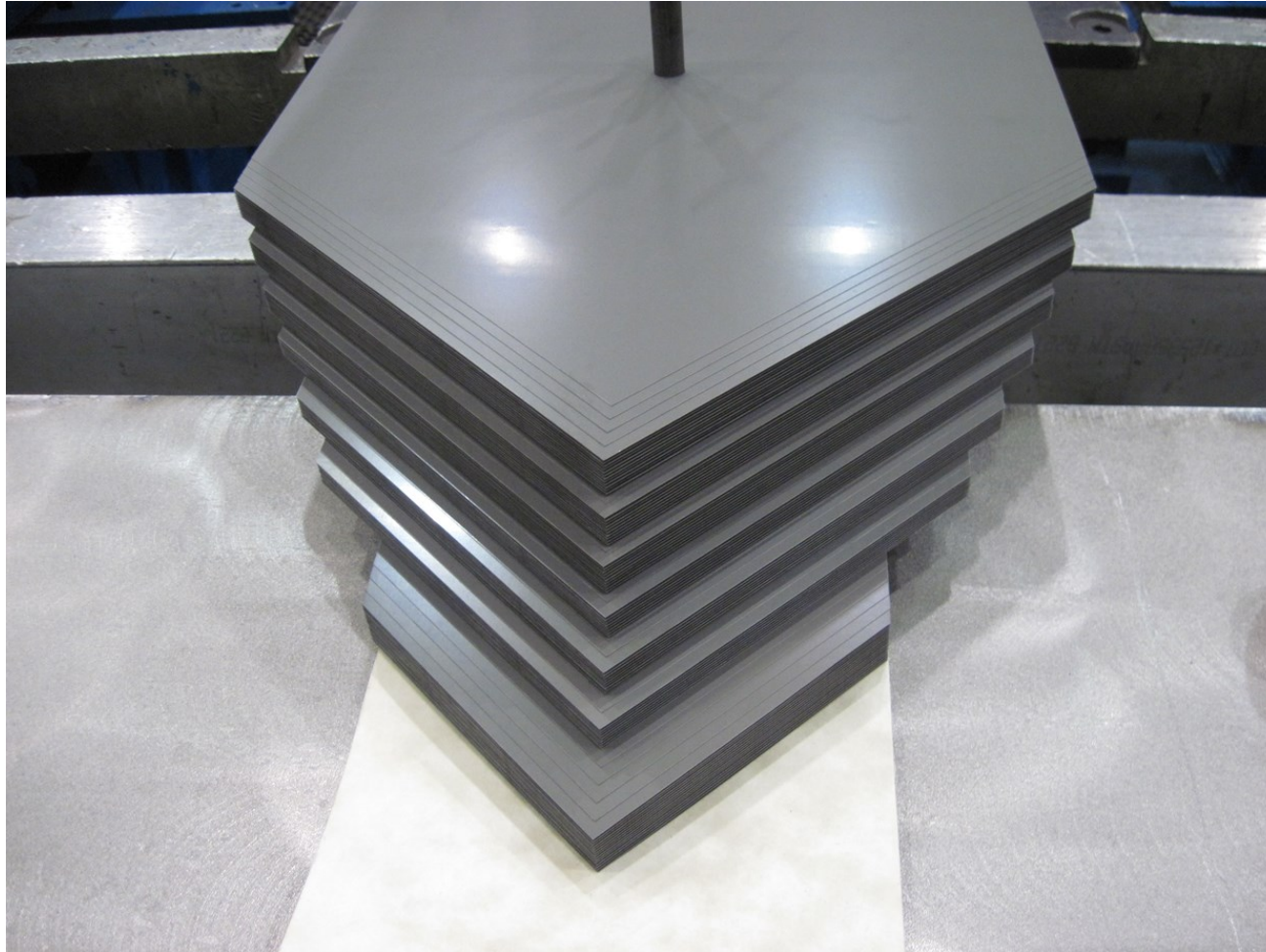
- Utilization factor (UF): Ratio of net cross-sectional area & gross area of core circle
  - ↑ # of core steps → ↑ UF → ↑ manufacturing cost
- Core with 6–15 core steps is cost-effective
- Optimizing core stacking step patterns → maximize core flux carrying area → more economical design



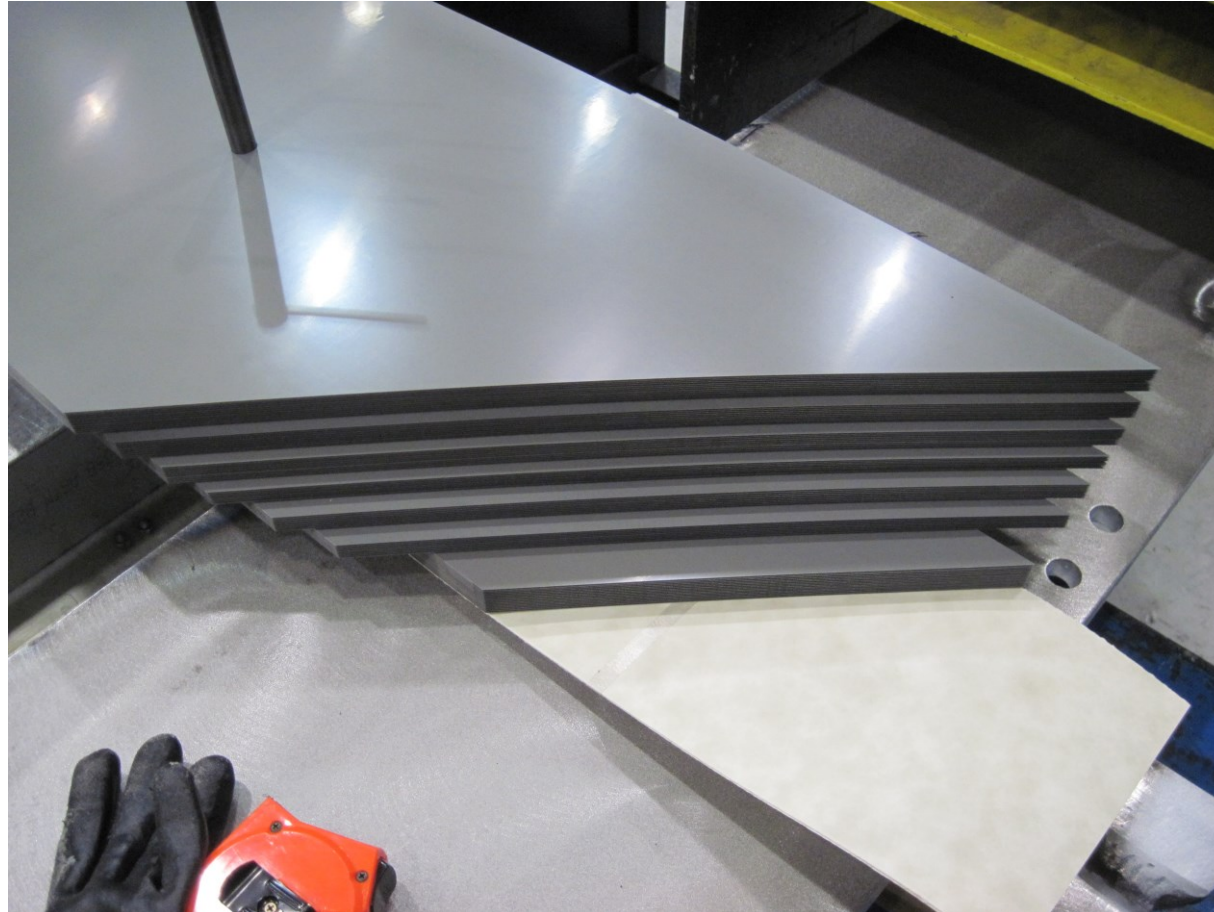
# Core Construction



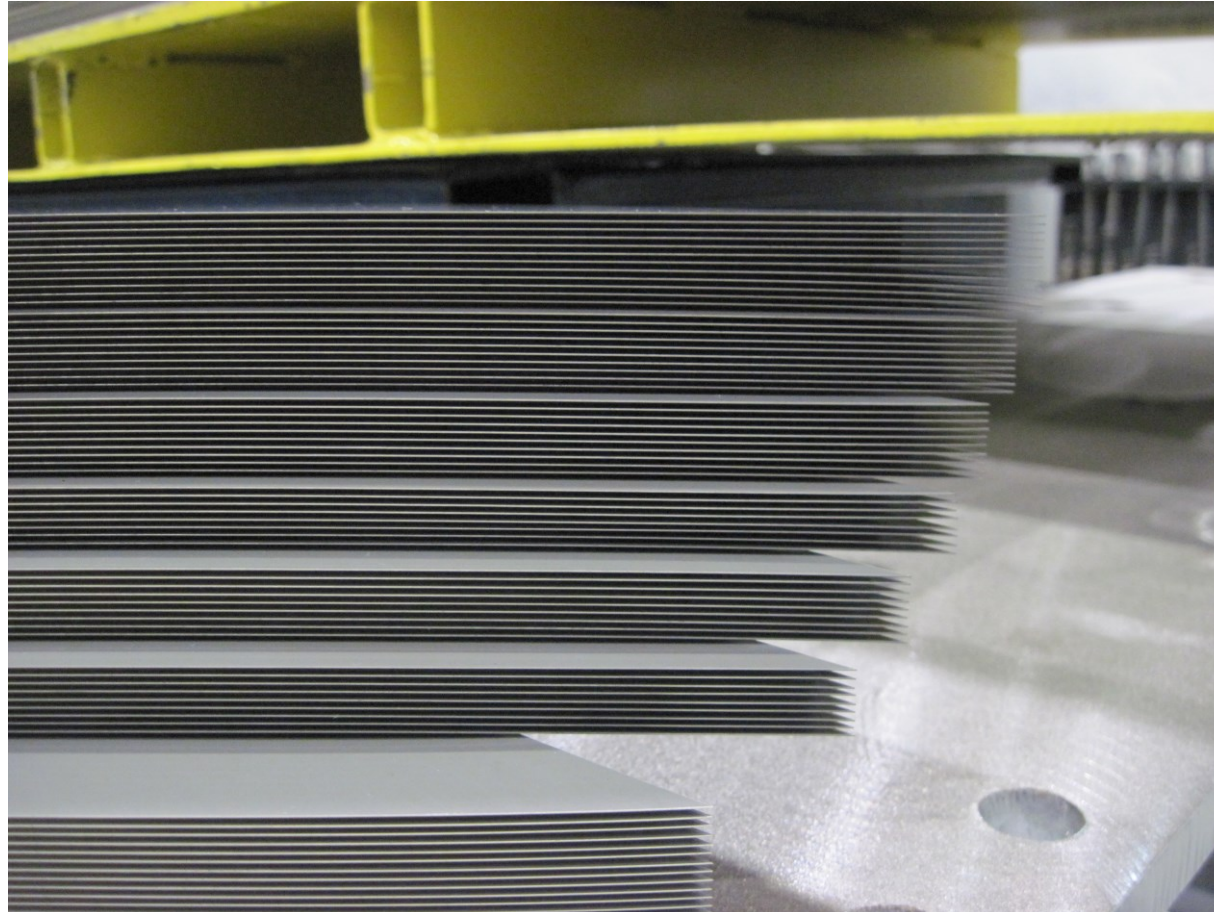
# Core Leg



# Core Leg (cont.)



# Core Leg (cont.)



# Bottom Yoke



# Core Assembly



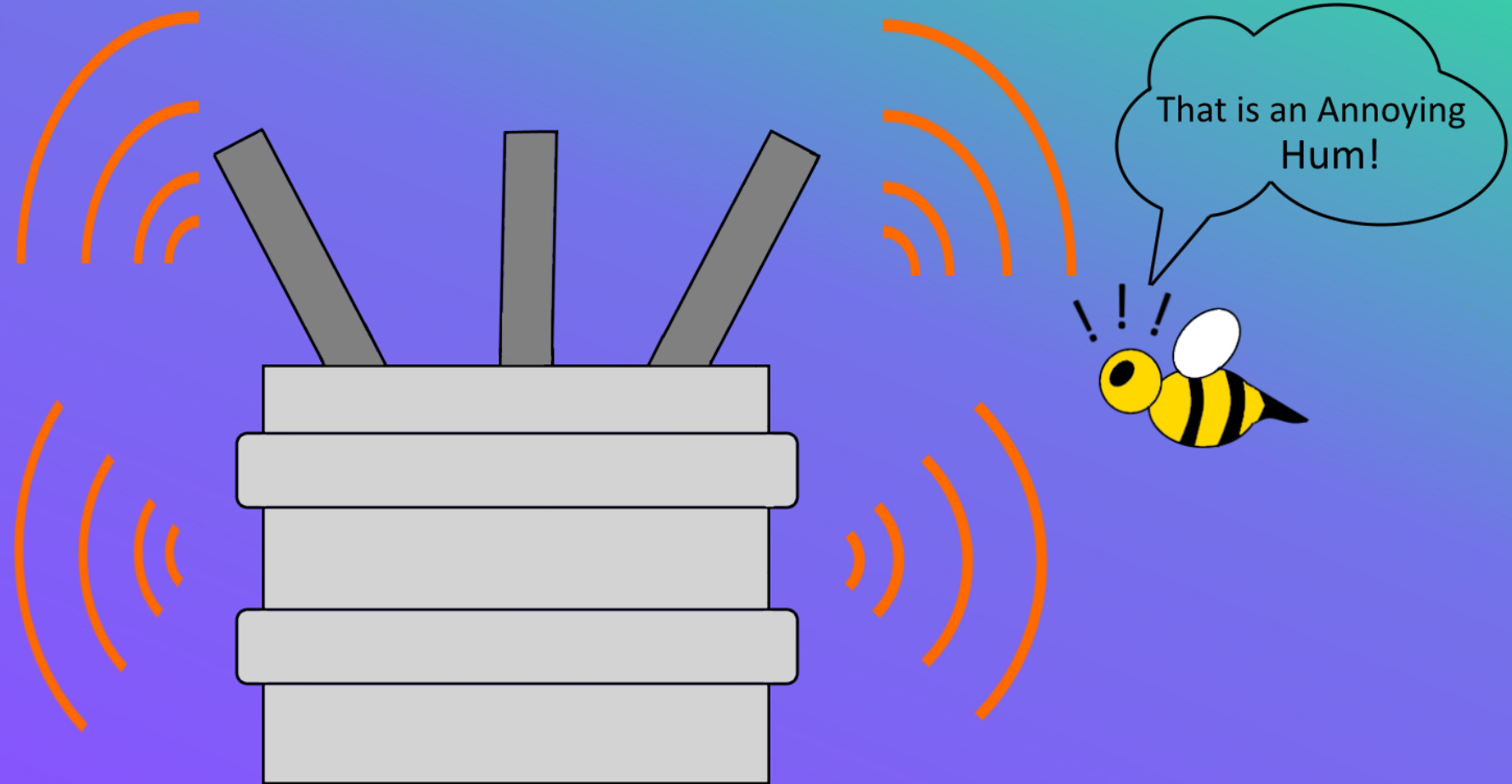
# Core “E” Assembly





# Core Related Problems & Solutions

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# Core Sound

## Annoying Magnetostriction

- Contraction of steel when magnetized
- Occurs 120x / sec in 60Hz unit
- Not linear to flux density
  - Harmonics ➡ Amplified noise

## Control of Sound

- Use of lower flux density
- Reduced air gaps at joints
- Step lap core construction
- Core banding

# Core Hot Spot Temperature

- Use of core ducts
- Lower flux density
- Use of Hi-B laser scribed material
- Reduction in corner losses – step lap core
- Splitting initial few steps of core leg

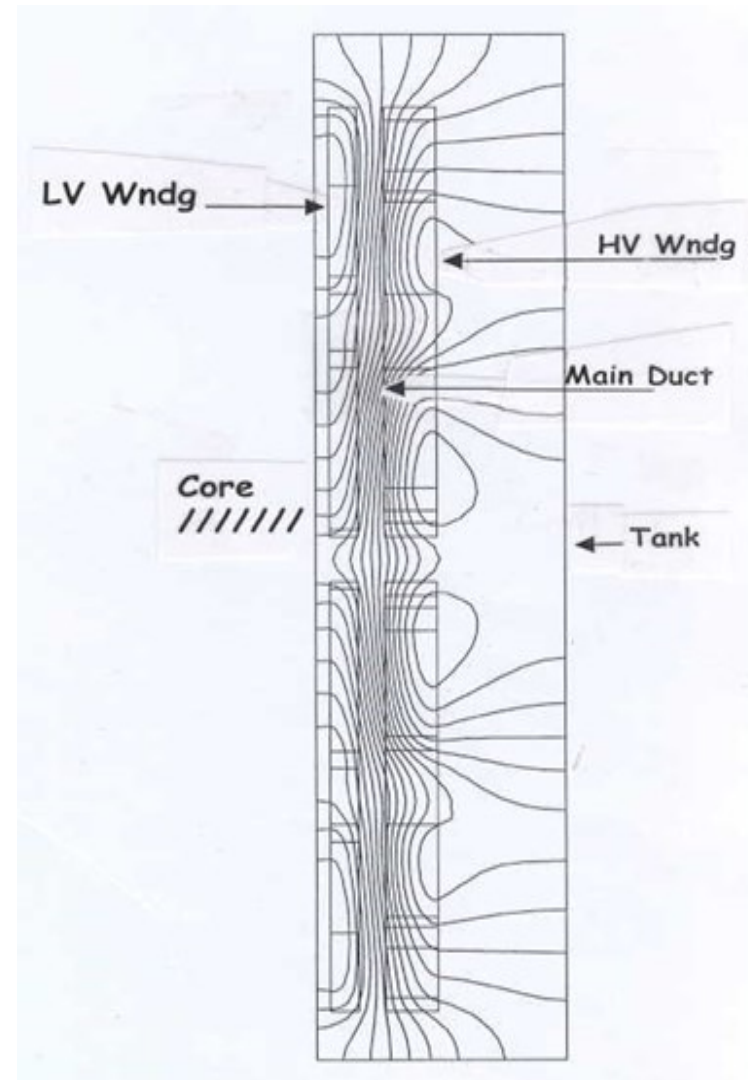
# Stray Losses

## Stray Flux

- Attract to and concentrate in:
  - Core clamps
  - Verticals (tie plates)
  - Tank Walls
- Excessive temperature rise

## Flux Shunts

- Attract and re-direct stray flux
- Provide low reluctance path





Contact

THANK YOU!

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